

USING SCILAB/SCICOS WITH RTAI-LAB

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1 Introduction

Computer Aided Control System Design (CACSD) subsumes a broad variety of computational tools and environments for control system design, real time simulation, with and without hardware in the loop, making the best use of high desktop computer power, graphical capabilities and ease of interaction with low hardware cost. Integrated CACSD software environments allow an interactive control system design process to be automated with respect to multi-objective performances evaluation and multi-parameter synthesis tuning. Visual decision support provides the engineer with the clues for interactively directing an automated search process to achieve a well balanced design under many conflicting objectives and constraints. Local/remote on line data down/upload makes it possible a seamless interaction with the control system, in order to supervise its operation and to adapt it to changing operational needs.

2 Installing the RTAI add-ons for Scilab/Scicos

2.1 Installing RTAI-Lab

2.1.1 Getting the files and the libraries

First of all you need RTAI-Lab. RTAI-Lab is an open project integrated in the Linux RTAI distribution. In order to run RTAI-Lab you need the following packages:

Linux RTAI download the last stable release from the RTAI homepage www.rtai.org

Mesa libraries download this libraries using the following steps:

1. Download MesaLib-5.0.1.tar.gz (from www.mesa3d.org) in a temporary directory (/tmp)
2. Untar the archive : `tar xvzf MesaLib-5.0.1.tar.gz`
3. `cd /tmp/Mesa-5.0.1`
4. `./configure --prefix=/usr/local --enable-static`

5. make
6. make install

Compile and install the EFLTK package

1. Download EFLTK from CVS in a temporary directory (/tmp)
`cvs -d:pserver:anonymous@cvs.sourceforge.net:/cvsroot/ede login`
 (press ENTER when CVS asks for password)
`cvs -z3 -d:pserver:anonymous@cvs.sourceforge.net:/cvsroot/ede co efltk`
2. `cd /tmp/efltk`
3. `./build.gcc -prefix=/usr/local -enable-xdbe -enable-opengl -enable-threads`
4. make install
5. `/sbin/ldconfig`

2.1.2 Installing RTAI and RTAI-Lab

Follow these steps in order to install a Linux RTAI

- Kernel
 1. Get a "vanilla" kernel from www.kernel.org
 2. Unpack the kernel
 3. Unpack Linux RTAI
 4. Patch the kernel with the adeos patch (`patch -p1 -i rtaidir/rtai-core/arch/i386/patches/kernel-version. patch`)
 5. make xconfig
 6. configure the kernel
 7. make bzImage
 8. make modules
 9. make modules_install
 10. make install
 11. fit lilo or grub for this new kernel
- install COMEDI : install comedi and comedilib from www.comedi.org
- install RTAI
 1. Go to the RTAI directory
 2. make xconfig
 3. Check "COMEDI support under LXRT" in the Add-ons submenu and give the directory where you installed comedilib
 4. Check "RTAI-Lab" under the RTAI-Lab submenu and add the directory where you installed the efltk libraries (normally "/usr/local")
 5. save and exit from xconfig
 6. run "make" and "make install"
- IMPORTANT: Add "/usr/realtime/bin" in your PATH environment variable, by modify the "/etc/profile" file or the ".bashrc" in the user direcorey

2.1.3 Installing Scilab

The first step is to download and install the full source Scilab-3.0 release from "www.scilab.org"; it contains Scicos already. Install scicos:

1. Go in the directory "/usr/local"
2. Unpack Scilab
3. cd scilab-3.0
4. ./configure
5. make all

2.1.4 Installing the RTAI add-ons for Scilab

Now follow these steps to properly install all the Scilab/Scicos add-ons for RTAI-Lab:

1. become superuser
2. go in the "macros" directory found here
3. modify eventually in the file "Makefile" the line

```
SCILAB_DIR = /usr/local/scilab-3.0
```

to fit your SCILAB installation

4. run "make install"

Each user who want to work with the Scilab/Scicos RTAI add-ons has to modify his own ".scilab" file. This operation can be done running as normal user "make user" in this "macros" directory. This command add the following lines to the user ".scilab" file:

```
load('SCI/macros/RTAI/lib')
%scicos_menu($+1)=[ 'RTAI', 'RTAI CodeGen' ]
scicos_pal($+1,:)=[ 'RTAI-Lib', 'SCI/macros/RTAI/RTAI-Lib.cosf' ]
```

These lines add the menu "RTAI→CodeGen" to the scicos window and the new RTAI-Lib.cosf library with the RTAI specific blocks to the scicos palette.

At this point you are ready to generate code for RTAI, using the new menu "RTAI→RTAICodeGen" in the scicos window.

3 A simple example

3.1 Scheme

In the following, a simple example will be analyzed. The system is represented by a transfer function

$$Gs(s) = \frac{20}{s^2 + 4s}$$

with unity feedback,

The system has been implemented as discrete-time transfer function

$$Gz(z) = 10^{-6} \frac{9.987z + 9.973}{z^2 - 1.996z + 0.996}$$

with a sampling time of $1ms$. Different signals are sent to scopes, meters, and leds.

The model is saved with the name "test".

3.2 Implementation under Scilab

3.2.1 Designing the scheme

First of all we have to design the system using scicos. We can get the different blocks from the scicos palettes in order to obtain the desired system. By the next step we have to integrate some I/O into our scheme. We implemented three methods:

- I/O can be choosed from a specific RTAI Library
- I/O were configured using an external application
- I/O were configured by hand

These methods can be mixed together.

3.2.2 Implementing I/O using the RTAI palette

Figure 1 represents the Scicos scheme of the example in this case.

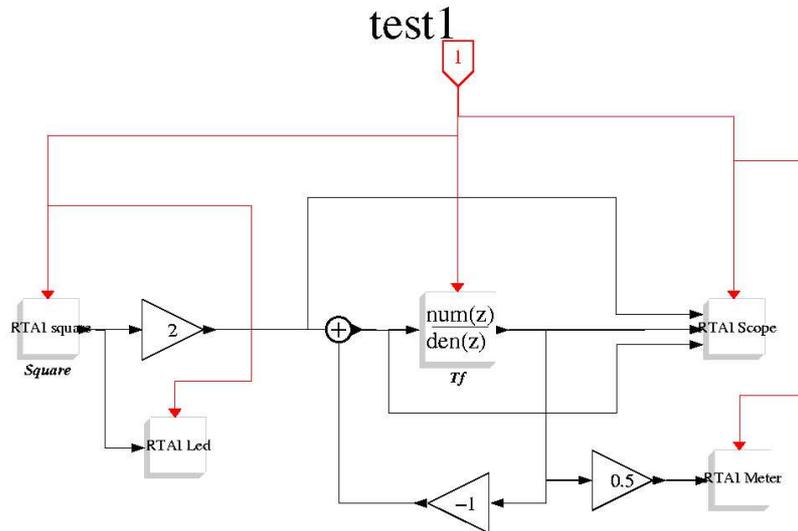


FIGURE 1: *Scicos scheme*

It is important to give to each I/O input and output a different Port nr:

- RTAI_scope: 1
- RTAI_meter: 2
- RTAI_led: 3
- RTAI_square: 1

In order to generate the code this scheme must be transformed into a "Super Block" which can be used to generate the code. The menu "Diagramm" "Region to Super Block" allows to select a part of the scheme and to put it into a "Super Block". We can access to the Super Block scheme simply by clicking on it. A good idea is to open the "Super Block" and to rename it ("Diagram" "Rename") to "test". This will be the name of the generated model and of the directory where the generated files are stored.

Now we can simply choose the menu "RTAI" "RTAICodeGen" to generate and compile the realtime code.

A dialog Box asks about some compilation parameters: the most important are

- the sampling time (the proposed value have been read from the clock block connected to the superblock).
- the name of the configuration file (default is "config").

After "OK" scicos performs the code generation and the compilation of the generated modules.

3.2.3 Implementing I/O using the external utility

Figure 2 represents the Scicos scheme of the example.

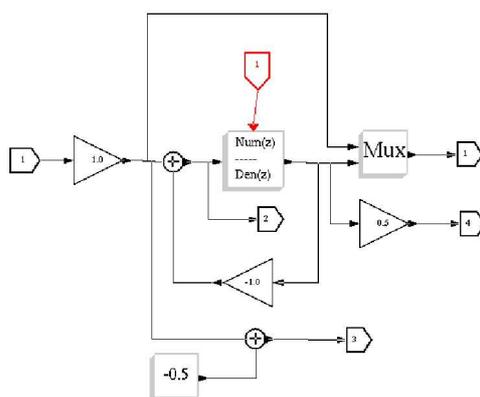


FIGURE 2: *Scicos scheme*

In order to generate the code this scheme must be transformed into a "Super Block" which can be used to generate the code. The menu "Diagramm" "Region to Super Block" allows to select a part of the scheme and to put it into a "Super Block". We can access to the Super Block scheme simply by clicking on it. A good idea is to open the "Super Block" and to rename it ("Diagram" "Rename")

to "test". This will be the name of the generated model and of the directory where the generated files are stored.

Now we can simply choose the menu "RTAI" "RTAICodeGen" to generate and compile the realtime code.

After the first dialog box you are asked about the creation of the IO configuration file. There are 3 possible choices here:

Yes scicos open "xgenconfig" to create or modify the IO configuration file, generates the <model_io>.c file and generates the standalone executable.

No scicos try to use an already created IO configuration file to generate the <model_io>.c file or leave it empty, and then performs the compilation of the standalone executable.

Cancel scicos stops the code generation.

If you give "Yes" a graphical application is open and you can configure the inputs and the outputs of the scheme. In this case you can give the following I/O:

- Input port 1: square
 - Amplitude: 1
 - Period: 10
 - Pulse width: 5
 - Bias: 0
 - Delay: 0
- Output port 1: rtai_scope
 - Number of signals: 2
 - Scope name: IO
- Output port 2: rtai_scope
 - Number of signals: 1
 - Scope name: U
- Output port 3: rtai_led
 - Number of leds: 1
 - Led name: LED
- Output port 4: rtai_meter
 - Meter name: METER

All this operations can be performed in a linux shell too:

xgenconfig a graphical environment to create IO configuration files. Simply run "xgenconfig -iN -oM -f<config_name>" to create the <config_name> configuration file with N input and M output.

Simply run "gen_io <mode> <config_name>" to create the <model_io>.c file and compile the executable "<model>" with the command

```
make -f <model>_Makefile <model>
```

4 I/O Blocks

4.1 Basics

I/O blocks are implemented in a library (libsciblk.a). There are 3 kind of I/O blocks:

1. Blocks which can be connected to an input or an output port (ex. `rtai_comedi_data`)
2. Blocks which can be connected only to an input port (ex. `step`)
3. Blocks which can be connectes only to an output port (ex. `rtai_scope`)

For each block in the config file the following (block dependent) items have been defined:

- the type (example: `rtai_scope`)
- input (inp) or output (out) port (where the block is connected)
- the port number to which the block is connected
- an identifier, a channel number or a maximal number of channels/signals for this block
- a name
- 5 parameters

4.2 Available blocks

The following IO Blocks have been implemented:

sinus creates a sinus input signal

square creates a square input signal

step creates a step input signal

rtai_scope sends signal(s) to the Rtai-Lab scope widget

rtai_led sends signal(s) to the Rtai-Lab leds widget

rtai_meter sends signal to the Rtai-Lab meter widget

mem allows to connect an output port to an input port of the scicos modul

rtai_comedi_data allows to connect COMEDI drivers for analog signals to the scicos modul (input or output)

rtai_comedi_dio allows to connect COMEDI drivers for digital signals to the scicos modul (input or output)

extdata gets the data from a file and creates a periodic input signal

pcan allows to connect the scicos modul to a Maxon driver through a bus can using a Peaks epp-dongle

cioquad4 build an input signal getting data from a Computer Boards CIO-QUAD4 digital encoder card

mbx_receive_if asynchronous receiver from a named mailbox (not blocking) for distributed systems

mbx_receive receiver from a named mailbox (blocking) for distributed systems

mbx_ovrwr_send sender to a named mailbox for distributed systems

These blocks are implemented both in the Scicos palette RTAI-Lib.cosf and for the xgenconfig utility.

The tables 1...17 show the parameters description of the IO Block.

io	inp
port	port Nr.
ch	not used
name	not used
sParam	not used yet
p1	Amplitude
p2	Frequency
p3	Phase
p4	Bias
p5	Delay

Table 1: Parameters for the IO block: *sinus*

io	inp
port	port Nr.
ch	not used
name	not used
sParam	not used yet
p1	Amplitude
p2	Period
p3	Impulse width
p4	Bias
p5	Delay

Table 2: Parameters for the IO block: *square*

5 Implementation of new user blocks

5.1 Implementing the code for a IO device

Different tools facilitate the implementation of new blocks. In order to implement new drivers some skeletons are provided:

- "template.c"
- "devtmpl.h"

io	inp
port	port Nr.
ch	not used
name	not used
sParam	not used yet
p1	Amplitude
p2	Delay
p3	not used
p4	not used
p5	not used

Table 3: Parameters for the IO block: *step*

io	out
port	port Nr.
ch	number of signals
name	Scope name
sParam	not used yet
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 4: Parameters for the IO block: *rtai_scope*

Using the command

```
gen_dev <model>
```

a file "`<model>.c`" will be created. This file contains all the needed functions to implement the driver as "input" and "output" driver. The utility "gen_dev" fills the file "devices.h" too.

The file "devstruct.h" contains the description of the structure used to store the block specific datas.

```
typedef struct devStr{
    int nch;
    char IOName[20];
    char sName[20];
    char sParam[20];
    double dParam[5];
    int i1;
    long l1;
    long l2;
    void * ptr;
}devStr;
```

A structure for input (inpDevStr) and a structure for output (outDevStr) are provided in "rtmain.c". Basically, the channel information can be stored under the field "nch", the name under "sName" and the 5 parameters p1...p5 into the

io	out
port	port Nr.
ch	number of leds (1 ... 16)
name	Led name
sParam	not used yet
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 5: Parameters for the IO block: *rtai_led*

io	out
port	port Nr.
ch	not used
name	Meter name
sParam	not used yet
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 6: Parameters for the IO block: *rtai_meter*

field "dParam". The field IOName is used to store the name of the IO Block needed by the online parameter modification.

The function interfaces in the generated file reflect the call implemented in <model.io.c> after calling "gen_io". Now the user can simply implement the code for the IO block.

5.2 Create the new library file

In order to generate the new library file with the new implemented IO Block, the user must modify the "Makefile.am" file, adding <model>.c to the list of the files to be compiled (libsciblk_a_SOURCES). The user have to launch "automake rtai-lab/scilab/devices/Makefile" from the RTAI root directory, followed by "./config.status". Now he can run "make" and "make install" in the scilab/devices directory. The libsciblk.a file will be created and copied in the library directory.

5.3 Adapting the "genconfig" and "xgenconfig" utility

The "genconfig" and "xgenconfig" utilities must now be modified to include the question for the new device parameters. This can be done by modifying the file "config_data.h", which contains two matrices of strings with the different questions. Simply increment the number of blocks (input or output or both) changing the values of the two "#define", and add a line to the repectives matrix providing the following strings:

io	inp or out
port	port Nr.
ch	id (0,1,2,...)
name	not used
sParam	not used yet
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 7: Parameters for the IO block: *mem*

io	inp or out
port	port Nr.
ch	ch or number of signals (device dependent)
name	"comediX"
sParam	not used yet
p1	range (device dependent)
p2	aref (device dependent)
p3	not used
p4	not used
p5	not used

Table 8: Parameters for the IO block: *rtai_comedi_data*

1. the name of the block
2. the question to the "nch" parameter
3. the question to the "sName" parameter
4. the question to the "sParam" parameter
5. the questions to the "p1"..."p5" parameters

Now we can simply run "make" and "make install" to generate and install the new 'xgenconfig' files.

io	inp
port	port Nr.
ch	ch or number of signals (device dependent)
name	"comediX"
sParam	not used yet
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 9: Parameters for the IO block: *rtai_comedi_dio*

io	out
port	port Nr.
ch	ch or number of signals (device dependent)
name	"comediX"
sParam	not used yet
p1	threshold
p2	not used
p3	not used
p4	not used
p5	not used

Table 10: Parameters for the IO block: *rtai_comedi_dio*

io	inp
port	port Nr.
ch	number of values
name	file name
sParam	not used yet
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 11: Parameters for the IO block: *extdata*

io	inp
port	port Nr.
ch	not used
name	CAN id (hex)
sParam	not used yet
p1	Proportional driver gain (PI)
p2	Integral driver gain (PI)
p3	not used
p4	not used
p5	not used

Table 12: Parameters for the IO block: *pcan*

io	out
port	port Nr.
ch	not used
name	CAN id (hex)
sParam	not used yet
p1	Proportional driver gain (PI)
p2	Integral driver gain (PI)
p3	not used
p4	not used
p5	not used

Table 13: Parameters for the IO block: *pcan*

io	inp
port	port Nr.
ch	modul number
name	Base Card Address
sParam	not used yet
p1	Resolution
p2	Precision (1,2,4)
p3	Rotation (-1,+1)
p4	Initial (0) or continous reset (1)
p5	not used

Table 14: Parameters for the IO block: *cioquad4*

io	inp
port	port Nr.
ch	number of signals
name	IP Address
sParam	MBX Name
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 15: Parameters for the IO block: *mbx_receive_if*

io	inp
port	port Nr.
ch	number of signals
name	IP Address
sParam	MBX Name
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 16: Parameters for the IO block: *mbx_receive*

io	out
port	port Nr.
ch	number of signals
name	IP Address
sParam	MBX Name
p1	not used
p2	not used
p3	not used
p4	not used
p5	not used

Table 17: Parameters for the IO block: *mbx_ovrwr_send*